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Otaide Ikechukwu Jackson Department of Mathematics, Edwin Clark University Kiagbodo, Nigeria

Ayinde Muhammed Abdullahi

Department of Mathematics, University of Abuja, Abuja, Nigeria

Isiaq Ajimoti Adam

Department of Mathematics, Al-Hikmah University, Ilorin Ilorin, Nigeria

Oyedepo Taiye

Department of Mathematics, Federal College of Dental Technology and Therapy, Enugu, Nigeria

Corresponding Author: Otaide Ikechukwu Jackson Department of Mathematics, Edwin Clark University Kiagbodo, Nigeria

Approximate solution of tenth-order boundary value problems using variational iteration techniques via chebyshev-hermite polynomials

Otaide Ikechukwu Jackson, Ayinde Muhammed Abdullahi, Isiaq Ajimoti Adam and Oyedepo Taiye

Abstract

The numerical solution of tenth order boundary value problems was obtained in this paper by employing the Variational iteration technique with Chebyshev-Hermite polynomials. The proposed modification involves constructing Chebyshev-Hermite polynomials for the given boundary value problems, which are then used as basis functions for the approximation. Numerical examples were also provided to demonstrate the proposed method's efficiency and applicability. The calculations were carried out using the Maple 18 software.

Keywords: Approximate solution, boundary value problems, chebyshev-hermite, variational iteration

Introduction

Consider a generalized boundary value problem of the form:

$$a_n \frac{d^j}{dz^j} v + a_{j-1} \frac{d^{j-1}}{dz^{j-1}} v + a_{j-2} \frac{d^{j-2}}{dz^{j-2}} v \dots a_1 \frac{d}{dz} v + a_0 v = f(z), a < z < b$$
⁽¹⁾

with boundary conditions

$$v(a) = A_1, v'(a) = A_2, v''(a) = A_3 \dots v^j(a) = A_i, v(b) = B_1, v'(b) = B_2,$$

$$v''(b) = B_3 \dots v^j(b) = B_r.$$
 (2)

These types of problems are useful in the mathematical modeling of real-world situations such as heat transfer, thermodynamics, viscoelastic flow, and other engineering sciences. Over the years, several numerical techniques for solving problems of this type have been developed. On a class of second-order boundary value problems, Islam et al. [10] used Bernoulli polynomials. Kasi Viswanadham and Sreenivasulu^[11] employed the Galerkin method with septic B-splines to solve tenth-order boundary value problems. Ali et al. [1] solved tenth-order boundary value problems using the reproducing kernel Hilbert space method. Iqbal^[9] used polynomial and non-polynomial cubic spline techniques to solve linear tenth-order boundary value problems. Ghazala ^[7] presented the homotopy analysis method to solve ninth-order boundary value problems. Mamadu and Njoseh ^[12] solved the first and second ordinary differential equations using the tau method and the tau-collocation approximation method. Noor and Mohyud-Din [14] used the variational iteration decomposition method to solve eight-order boundary value problems. Zhou and Xu^[17] recently proposed a collocation method for numerical solutions of linear and nonlinear singular boundary value problems based on Laguerre wavelets. Avatullah and Mirna^[2] used Hermite polynomials to solve optimal control problems in their Quintic B-spline collocation method for second-order mixed boundary value problems. Biala and Jator^[6] presented a family of boundary value methods for second-order boundary value problems.

Su ^[16] presented a boundary value problem for a coupled system of nonlinear fractional differential equations. For the solution of seventh-order boundary value problems, Shahid and Iftikhar ^[15] used the variational iteration homotopy perturbation method. He ^[18] employed the homotopy perturbation method for solving boundary value problems.

Benmezai & Sedkaoui^[4] also investigated the existence of a positive solution to the third-order boundary value problem. The work of the aforementioned researchers inspired us to use the variational iteration technique with Chebyshev-Hermite polynomials to solve a tenth-order boundary value problem in this paper. The correction function is corrected for boundary value problems in this proposed method, and the Lagrange multiplier is optimally computed using variational theory. So far, the proposed method has proven to be effective, with encouraging and consistent results. Finally, the solution is presented as an infinite series that typically converges to an accurate solution.

Standard Variational Iteration Technique

Consider the following general differential equation to demonstrate the basic concept of the technique:

$$Lv + Nv - g(z) = 0, (3)$$

Where L is a linear operator, J a nonlinear operator and g(z) is the inhomogeneous term According to variational iteration method, we can construct a correction functional as follows

$$v_{r+1} = v_r(z) + \int_0^z \lambda(t) \left(L v_r(t) + N \widetilde{v_r(t)} - g(t) \right) dt$$
⁽⁴⁾

Where $\lambda(t)$ a Lagrange multiplier that can be optimally is identified using a Variational iteration technique. The subscripts represent the nth closest approximation. $\tilde{v_r}$ is regarded as a restricted variation. i.e., $\tilde{v_r}=0$. The relationship (4) is known as a correction functional. Because of the precise identification of the Lagrange multiplier, linear problems can be solved in a single iteration step. In this method, we must optimally determine the Lagrange multiplier $\lambda(t)$ optimally, and thus the successive approximation of solution v will be easily obtained by employing the Lagrange multiplier and our v_0 , and the solution is given by

$$\lim_{r \to \infty} v_r = v \tag{5}$$

The Lagrange Multiplier, which can be defined as follows,

$$\lambda(t) = (-1)^{j} \frac{1}{(j-1)!} (t-z)^{j-1}$$
(6)

Also plays an important role in determining the solution to the problem.

Chebyshev Polynomials

Chebyshev-Hermite polynomials, also known as "Probabilist's Hermite polynomials," are defined by

$$H_{e_j}(z) = (-1)^j e^{\frac{z^2}{2}} \frac{d^j}{dz^j} e^{-\frac{j^2}{2}}$$
(7)

Hence, the first five Chebyshev-Hermite polynomials are as follows:

Modified Variational Iteration Technique Using Chebyshev And Shifted Chebyshev Polynomials of the Fourth Kind (MVITCP-SCP)

Using (3) and (4), we assume an approximate solution of the form

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$$v_{r,J-1}(x) = \sum_{r=0}^{J-1} a_{r,J-1} H_{e_{r,J-1}}(z)$$
⁽⁹⁾

Where $H_{e_{r,J-1}(z)}$ are Hermite polynomials, $a_{r,J-1}$ are constants to be determined, and J the degree of approximant. Hence we obtain the following iterative method

$$v_{r+1,J-1}(z) = \sum_{r=0}^{J-1} a_{r,J-1} H_{r,J-1}(z) + \int_{0}^{z} \lambda(t) \left(L \sum_{r=0}^{J-1} a_{r,J-1} H_{e_{r,J-1}}(t) + N_l \sum_{r=0}^{J-1} a_{r,J-1} H_{e_{r,J-1}}(t) \right) dt$$
(10)

Numerical Applications

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In this section, we solved three examples using the proposed method, and the numerical results also demonstrate the proposed scheme's accuracy and efficiency.

Numerical Example 1: Considers the following tenth order boundary value problem ^[1]

$$v^{(10)} + v = -10(2zsinz - 9cosz), \quad -1 \le z \le 1$$

$$v(-1) = v(1) = 0, \ v'(1) = -v'(-1) = 2cos1, \ v''(-1) = v''(1) = 2cos1 - 4sin1_{(12)}$$

The exact solution for the problem is

$$v = (z^2 - 1)cosz. \tag{13}$$

The correction functional for the boundary value problem (11) and (12) is given as

$$v_{r+1} = v_r(z) + \int_0^z \lambda(t) \left(v^{(10)} + v + 10(2tsint - 9cost) \right) dt$$

Where, $\lambda(t) = \frac{(-1)^{10}(t-z)^9}{9!}$ is the Lagrange multiplier. Applying the modified variational iteration technique using the Chebyshev-Hermite polynomials, we assume an approximate solution of the form

$$v_{j,9}(z) = \sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(z) \tag{14}$$

Hence, we get the following iterative formula:

$$v_{r+1,J-1}(z) = \sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(z) + \int_{0}^{z} \frac{(t-z)^{9}}{9!} \left(\frac{d^{10}}{dt^{10}} \left(\sum_{z=0}^{9} a_{r,9} H_{e_{r,9}}(t) \right) + 10(2tsint - 9cost) \right) dt$$
(15)

Hence, using (8) iterating and applying the boundary conditions (12) the values of the unknown constants can be determined as follows

$$a_{0,9} = -0.627604168$$
, $a_{1,9} = 0$, $a_{2,9} = -0.406250002$, $a_{3,9} = 0$, $a_{4,9} = -0.192708332$, $a_{5,9} = 0$, $a_{6,9} = 0.0034722223$, $a_{7,9} = 0$, $a_{8,9} = -0.00141369048$, $a_{9,9} = 0$

Consequently, the series solution is given as

$$v(x) = 0.99999999999 + 4.79509654210^{-14}x^{18} - 1.15185403810^{-11}x^{16} + 2.09914644510^{-9}x^{14} - 2.777660867910^{-7}x^{12} + 0.00002507716049x^{10} - 0.00141369048x^8 + 0.04305555574x^6 - 0.5416666673x^4 + 1.499999995x^2$$
(16)

Numerical Example 2: Considers the following tenth order boundary value problem^[1]

$$v^{(10)} - (z^2 - 2z)v = 10\cos z - (z - 1)^3 \sin z, \ -1 \le z \le 1$$

$$v(-1) = 2\sin 1, \ v(1) = 0, \ v'(-1) = -2\cos 1 - \sin 1, \ v'(1) = \sin 1$$

$$v''(-1) = 2\cos 1 - 2\sin 1, \ v''(1) = 2\cos 1, \ v'''(-1) = 2\cos 1 + 3\sin 1,$$

$$v'''(1) = -3\sin 1, \ v^{(4)}(-1) = -4\cos 1 + 2\sin 1, \ v^{(4)}(1) = -4\cos 1.$$
(18)

The exct solution for the problem is

$$v(z) = (z-1)sinz \tag{19}$$

The correction functional for the boundary value problem (18) and (19) is given as

$$v_{j+1} = v_j(z) + \int_0^z \lambda(t) \left(v^{(10)} - (t^2 - 2t)v - 10cost + (t - 1)^3 sint \right) dt$$
⁽²⁰⁾

where, $\lambda(t) = \frac{(-1)^{10}(t-z)^9}{9!}$ is the Lagrange multiplier. Applying the modified variational iteration technique using the Chebyshev-Hermite polynomials, we assume an approximate solution of the form

$$v_{j,9}(z) = \sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(z)$$
⁽²¹⁾

Hence, we get the following iterative formula:

$$\begin{aligned} v_{j+1,J-1}(z) &= \sum_{j=0}^{9} a_{r,9} H_{e_{r,9}}(x) + \int_{0}^{z} \frac{(t-z)^{9}}{9!} \left(\frac{d^{10}}{dt^{10}} \left(\sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(t) \right) - (t^{2} - 2t) \sum_{i=0}^{9} a_{i,9} H_{e_{i,9}}(t) - 10 cost + (t-1)^{3} sint \right) dt \\ v_{j+1,J-1}(z) &= a_{0,9} H_{e_{0,9}}(z) + a_{1,9} H_{e_{1,9}}(z) + a_{2,9} H_{e_{2,9}}(z) + a_{3,9} H_{e_{3,9}}(z) + a_{4,9} H_{e_{4,9}}(z) \\ + a_{5,9} H_{e_{5,9}}(z) + a_{6,9} H_{e_{6,9}}(z) + a_{7,9} H_{e_{7,9}}(z) + a_{8,9} H_{e_{8,9}}(z) + a_{9,9} H_{e_{9,9}}(z) + \end{aligned}$$

$$(22)$$

$$\int_{0}^{z} \frac{(t-z)^{9}}{9!} \left(\frac{d^{10}}{dt^{10}} \left(\sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(t) \right) - (t^{2} - 2t) \sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(t) - 10 cost + (t - 1)^{3} sint \right) dt$$
(23)

As a result of (8), iteration, and application of the boundary conditions (18), the values of the unknown constants can be determined as follows

$$\begin{aligned} a_{0,9} &= 0.60416666666, \ a_{1,9} &= -0.60677081, \\ a_{2,9} &= 0.2916666669, \\ a_{3,9} &= 0.1006945, \\ a_{4,9} &= -0.0833333333, \ a_{5,9} &= -0.00520833, \\ a_{6,9} &= 0.0027777779, \\ a_{7,9} &= 0.00099205, \ a_{8,9} &= -0.00019841271, \\ a_{9,9} &= -0.0000027557 \end{aligned}$$

Consequently, the series solution is given as

$$\begin{aligned} v(z) &= 4.306071975 \, 10^{-18} z^{21} - 4.1104302 \, 10^{-18} z^{20} - 8.2132521 \, 10^{-18} z^{19} \\ &- 2.81085018 \, 10^{-15} z^{17} - 7.64719518 \, 10^{-13} z^{16} + 7.6470244110^{-13} z^{15} \\ &+ 1.605905292 \, 10^{-10} z^{14} - 1.605903841 \, 10^{-10} z^{13} - 2.50521090410^{-8} z^{12} \\ &+ 2.505210861 \, 10^{-8} z^{11} - 0.0000027557 z^9 - 0.0001984127 z^8 \\ &+ 0.0001984102 x^7 + 0.00833333378 x^6 - 0.0083332896 x^5 \\ &- 0.1666666706 x^4 + 0.1666665060 x^3 + 1.00000011 x^3 \\ &- 0.9999999215 x - \frac{1}{851515702861824000} x^{32} + \frac{1}{362880} x^{10} - 4.4 \, 10^{-9} \end{aligned}$$

Numerical Example 3: Considers the following tenth order boundary value problem^[1]

$$v^{(10)} = -(80 + 19z + z^2)e^z, \quad 0 \le z \le 1$$
(25)

$$v(0) = 0, v(1) = 0, v''(0) = 0, v''(1) = -4e, v^{(4)}(0) = -8, v^{(4)}(1) = -16e,$$

$$v^{(6)}(0) = -24_{s}v^{(6)}(1) = -36e, v^{(8)}(0) = -48, v^{(8)}(1) = -64e,$$
 (26)

The exact solution for the problem is

$$v(z) = z(1-z)e^z \tag{27}$$

The correction functional for the boundary value problem (25) and (26) is given as

$$v_{j+1} = v_r(z) + \int_0^z \lambda(t) \left(v^{(10)} + (80 + 19t + t^2)e^t \right) dt$$
⁽²⁸⁾

 $\lambda(t) = \frac{(-1)^{10}(t-z)^9}{9!}$ is the Lagrange multiplier Applying the modified variational iteration technique using the Chebyshev-Hermite polynomials, we assume an approximate

solution of the form

$$v_{j,9}(z) = \sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(z)$$
⁽²⁹⁾

Hence, we get the following iterative formula:

$$v_{j+1,J-1}(z) = \sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(z) + \int_{0}^{z} \frac{(t-z)^{9}}{9!} \left(\frac{d^{10}}{dt^{10}} \left(\sum_{r=0}^{9} a_{r,9} H_{e_{r,9}}(t) \right) + (80 + 19t + t^{2})e^{t} \right) dt$$
(30)

$$\begin{aligned} v_{j+1,J-1}(z) &= a_{0,9}H_{e_{0,9}}(z) + a_{1,9}H_{e_{1,9}}(z) + a_{2,9}H_{e_{2,9}}(z) + a_{3,9}H_{e_{3,9}}(z) + a_{4,9}H_{e_{4,9}}(z) \\ &+ a_{5,9}H_{e_{5,9}}(z) + a_{6,9}H_{e_{6,9}}(z) + a_{7,9}H_{e_{7,9}}(z) + a_{8,9}H_{e_{8,9}}(z) + a_{9,9}H_{e_{9,9}}(z) \\ &+ \int_{0}^{z} \frac{(t-z)^{9}}{9!} \left(\frac{d^{10}}{dt^{10}} \Big(\sum_{r=0}^{9} a_{r,9}H_{e_{r,9}}(t) \Big) + (80 + 19t + t^{2})e^{t} \right) dt \end{aligned}$$
(31)

As a result of (8), iteration, and application of the boundary conditions (26), the values of the unknown constants can be

determined as follows

$$a_{0,9} = -1.625000000, \ a_{1,9} = -3.268229405, \ a_{2,9} = -4, \ a_{3,9} = -2.697917067,$$

$$a_{4,9} = -1.083333333, \ a_{5,9} = -0.3364584897, \ a_{6,9} = -0.0666666666667,$$

$$a_{7,9} = -0.01319446435, a_{8,9} = -0.001190476190, a_{9,9} = -0.0001736119192$$

Consequently, the series solution is given as

$$v(z) = \frac{1}{114328101888000} z^{18} - \frac{1}{2032499589120} z^{17} - \frac{1}{93405312000} z^{16} - \frac{1}{6706022400} z^{15}$$
$$-\frac{1}{518918400} z^{14} - \frac{1}{43545600} z^{13} - \frac{1}{3991680} z^{12} - \frac{1}{403200} z^{11} - \frac{1}{45360} z^{10}$$
$$-0.0001736119192z^9 - 0.001190476190z^8 - 0.006944435259z^7 - \frac{1}{2000} z^{10} - \frac{1}{200} z^{10} - \frac{1}{2000} z^{10} - \frac{1}{200} z^{10} - \frac{1}{2000} z^{10} - \frac{1}{200} z^{10} - \frac{1}{200} z^{10} - \frac{1}{2000} z^{10} - \frac{1}{200} z^$$

 $0.0333333335z^{6} - 0.1250000438z^{5} - 0.3333333329z^{4} - 0.4999999992^{3} - 2.10^{-9} + 0.999999943 + 1.10^{-9}$ (32)

Tables

Table 1: The result of the proposed method compared Galerkin method with septic B-spline [11]

| Z | Exact solution | Approximate solution | Absolute Error by the proposed method | GMSB-s Error |
|------|----------------|----------------------|---------------------------------------|--------------|
| -0.8 | -0.2508144153 | -0.2508144152 | 1.000000e-10 | 5.483627e-06 |
| -0.6 | -0.5282147935 | -0.5282147918 | 1.700000e-09 | 9.536743e-07 |
| -0.4 | -0.7736912350 | -0.7736912328 | 2.200000e-09 | 8.702278e-06 |
| -0.2 | -0.9408639147 | -0.9408639122 | 2.500000e-09 | 2.980232e-07 |
| 0.0 | -1.000000000 | -0.9999999969 | 3.100000e-09 | 1.955032e-05 |
| 0.2 | -0.9408639147 | -0.9408639122 | 2.500000e-09 | 2.920628e-05 |
| 0.4 | -0.7736912350 | -0.7736912328 | 2.200000e-09 | 2.169609e-05 |
| 0.6 | -0.5282147935 | -0.5282147918 | 1.700000e-09 | 7.390976e-06 |
| 0.8 | -0.2508144153 | -0.2508144152 | 1.000000e-10 | 7.450581e-07 |

Table 2: The result of the proposed method compared with Reproducing Kernel Hilbert Space Method ^[1]

| Ζ | Exact solution | Approximate solution | Absolute Error by the proposed method | GMSB-s Error |
|------|----------------|----------------------|---------------------------------------|--------------|
| -0.8 | 1.2912409640 | 1.291240970 | 6.000000e-09 | 4.649162e-06 |
| -0.6 | 0.9034279574 | 0.9034279406 | 1.680000e-08 | 1.329184e-05 |
| -0.4 | 0.5451856792 | 0.5451856549 | 2.430000e-08 | 2.050400e-05 |
| -0.2 | 0.2384031970 | 0.2384031786 | 1.840000e-08 | 9.477139e-06 |
| 0.0 | 0.0000000000 | 4.400000e-09 | 4.400000e-09 | 2.731677e-06 |
| 0.2 | -0.1589354646 | -0.1589354542 | 1.040000e-08 | 1.458824e-05 |
| 0.4 | -0.2336510054 | -0.2336509864 | 1.900000e-08 | 2.110004e-05 |
| 0.6 | -0.2258569894 | -0.2258569743 | 1.510000e-08 | 1.908839e-05 |
| 0.8 | -0.1434712182 | -0.1434712222 | 4.000000e-09 | 1.342595e-05 |

Table 3: The result of the proposed method compared with Reproducing Kernel Hilbert Space Method [1]

| Z | Exact solution | Absolute Error by the proposed method | AE (RKHSM) [2] | AE (NPCSM) [3] | AE (PCSM) ^[3] |
|-----|----------------|---------------------------------------|----------------|----------------|---------------------------------|
| 0.2 | 0.195424441 | 9.800000e-09 | 3.330000e-08 | 2.433000e-07 | 3.982000e-04 |
| 0.4 | 0.358037927 | 1.680000e-08 | 7.031000e-08 | 3.986000e-07 | 6.663000e-04 |
| 0.6 | 0.358037927 | 1.720000e-08 | 6.076000e-08 | 4.428000e-07 | 7.598000e-04 |
| 0.8 | 0.356086549 | 1.160000e-08 | 2.682000e-08 | 3.328000e-07 | 5.885000e-04 |

Conclusions

The modified Variational iteration technique with Chebyshev-Hermite polynomials was successfully applied in this paper to obtain numerical solutions to tenth order boundary value problems. Chebyshev-Hermite polynomials are combined with Variational iteration techniques in the modification. The method produces rapidly converging series solutions, which are common in physical problems. Tables (1), (2), and (3) show that when compared to methods in the literature, the proposed method produces a better result. Finally, the numerical results demonstrated that the current method is a powerful mathematical tool for solving the class of problems under consideration.

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